

Sphinx

A Co-Evolution Framework for Model Refactoring and Proof Adaptation in Cyber-Physical Systems

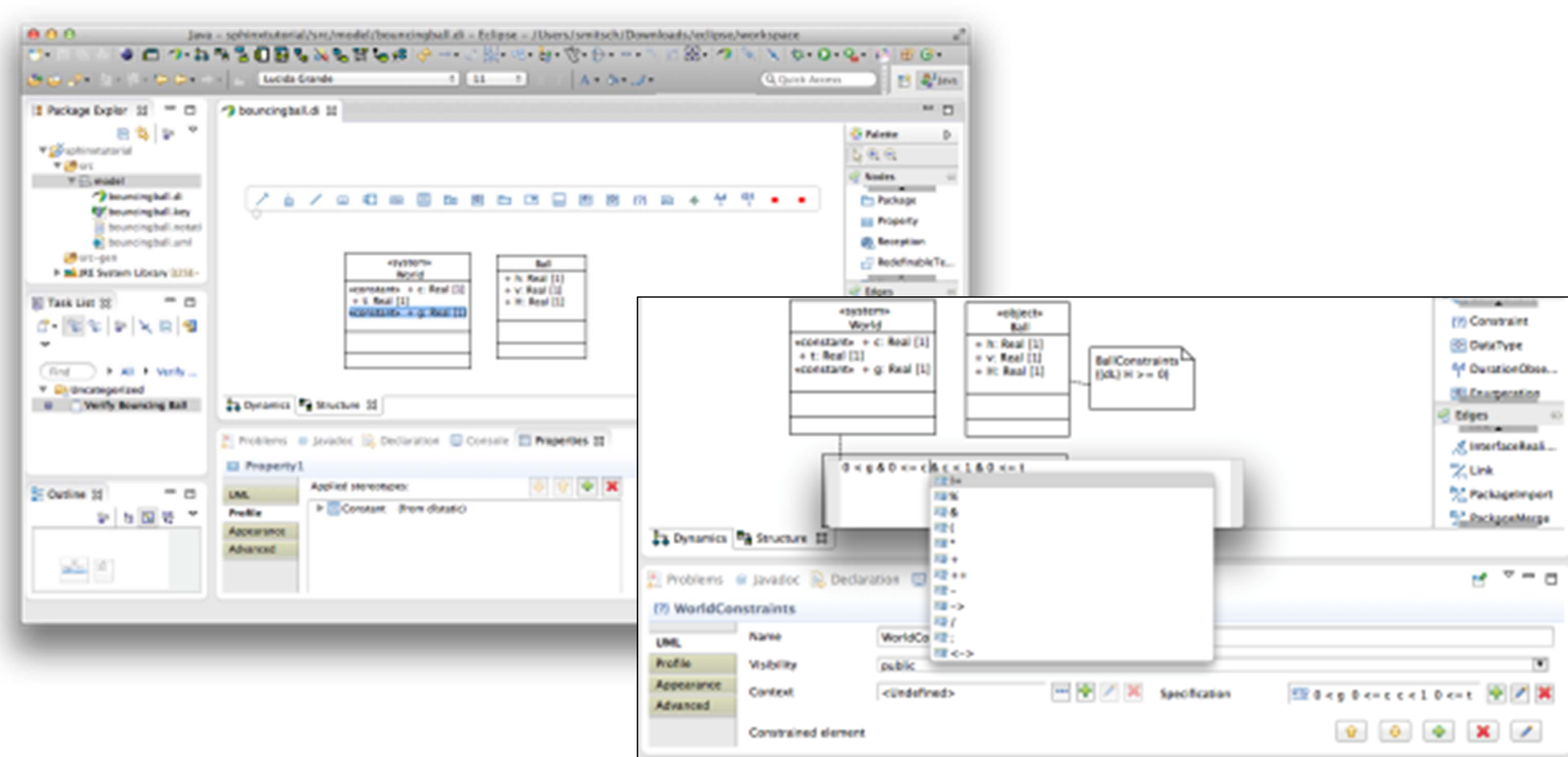
Overview

Hybrid systems with both discrete and continuous dynamics are an important model for real-world physical systems. The key challenge is how to ensure their correct functioning w.r.t. safety requirements. Promising techniques to ensure safety seem to be model-driven engineering to develop hybrid systems in a well-defined and traceable manner, and formal verification to prove their correctness. Their combination forms the vision of verification-driven engineering. It is not uncommon for verification teams to consist of many players with diverse expertise. We introduce a verification-driven engineering toolset that with tools for

- (i) modeling hybrid systems,
 - (ii) exchanging and comparing models and proofs, and
 - (iii) managing verification tasks.
- This toolset makes it easier to tackle large-scale verification tasks.

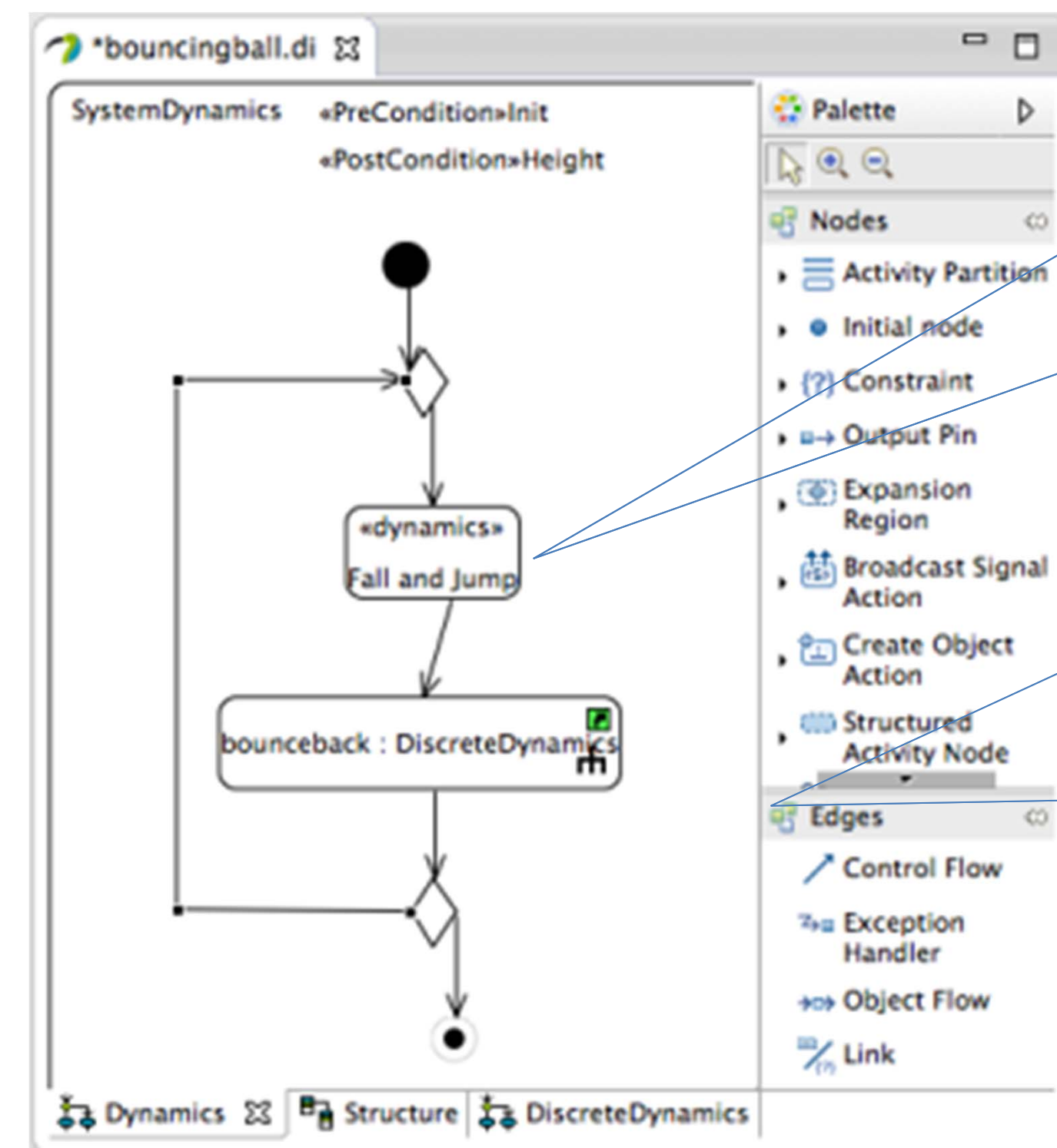
Graphical Modeling

Structure: UML Class Diagram

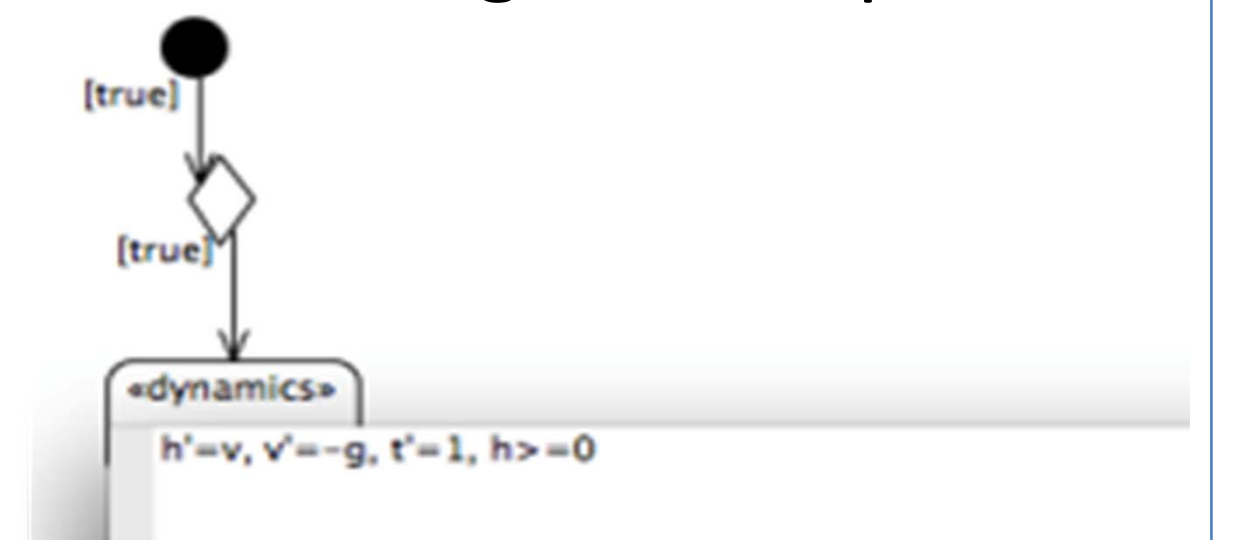


Constraint Popup Editor

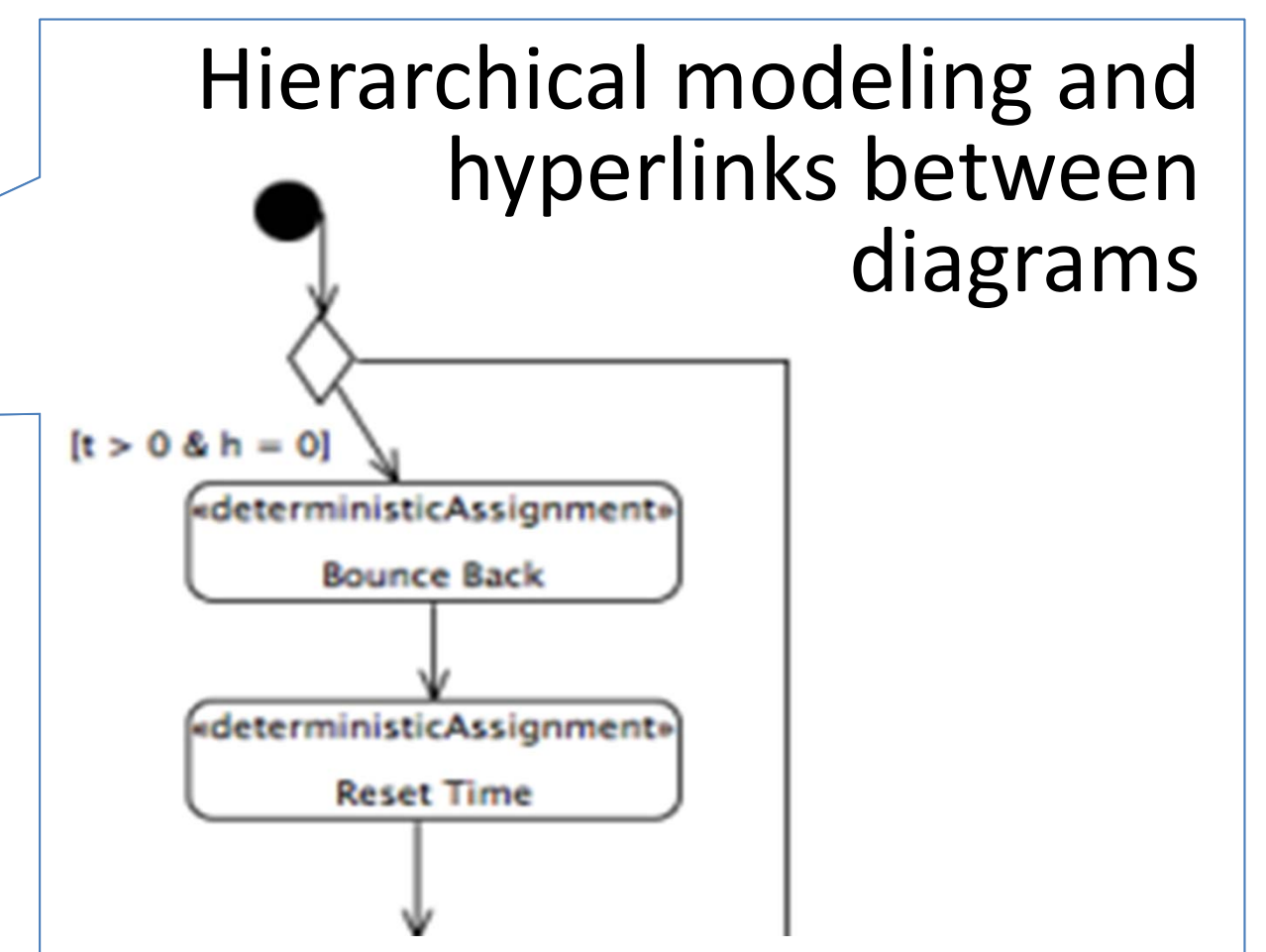
Dynamics: UML Activity Diagram



Popup editor for differential-algebraic equations



Hierarchical modeling and hyperlinks between diagrams



Textual Modeling

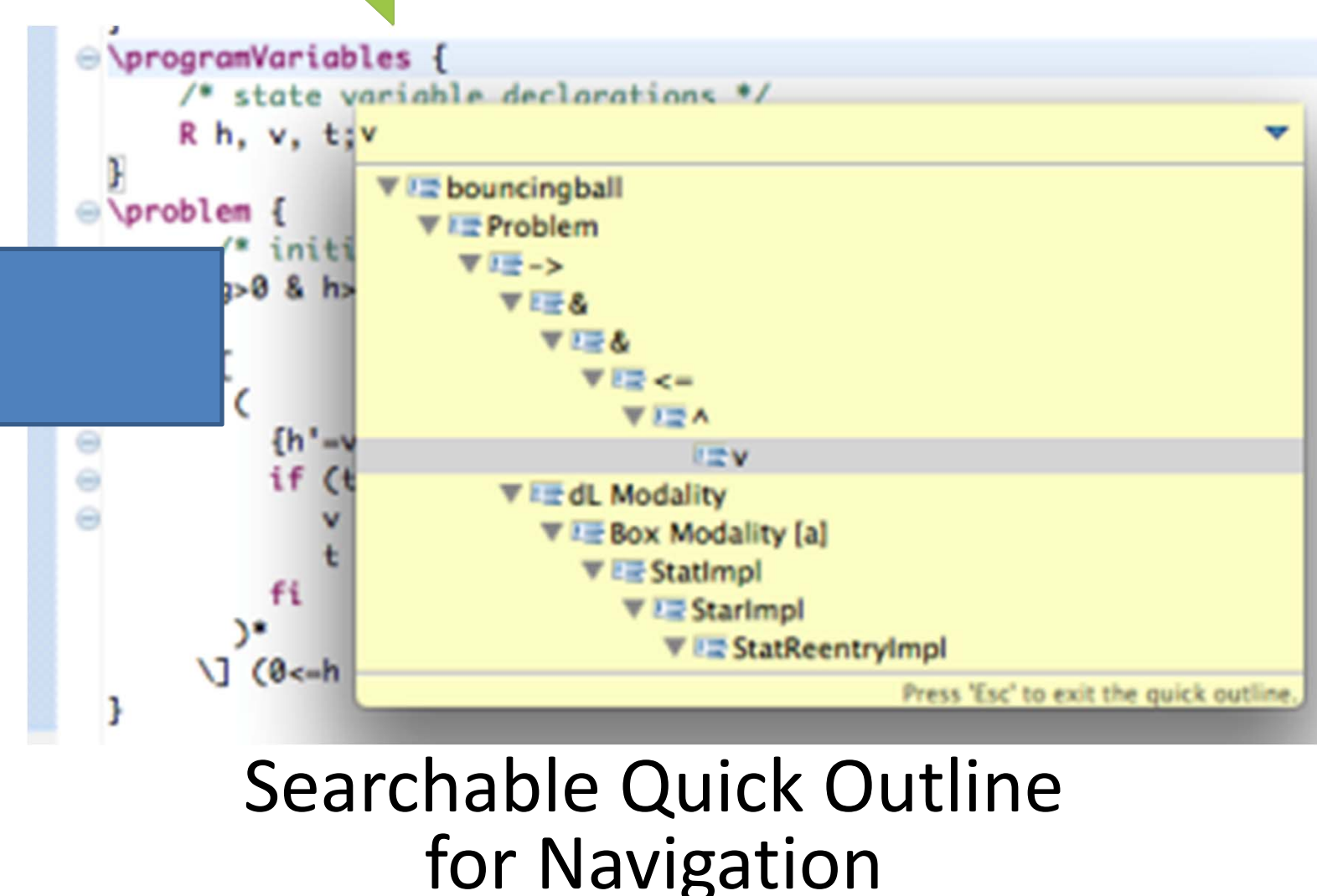
```

problem {
  /* initial state characterization */
  g>0 & h>=0 & t>=0 & 0<=c & c<1 & v^2 <= 2*g*(H-h) & H>=0
}
  
```

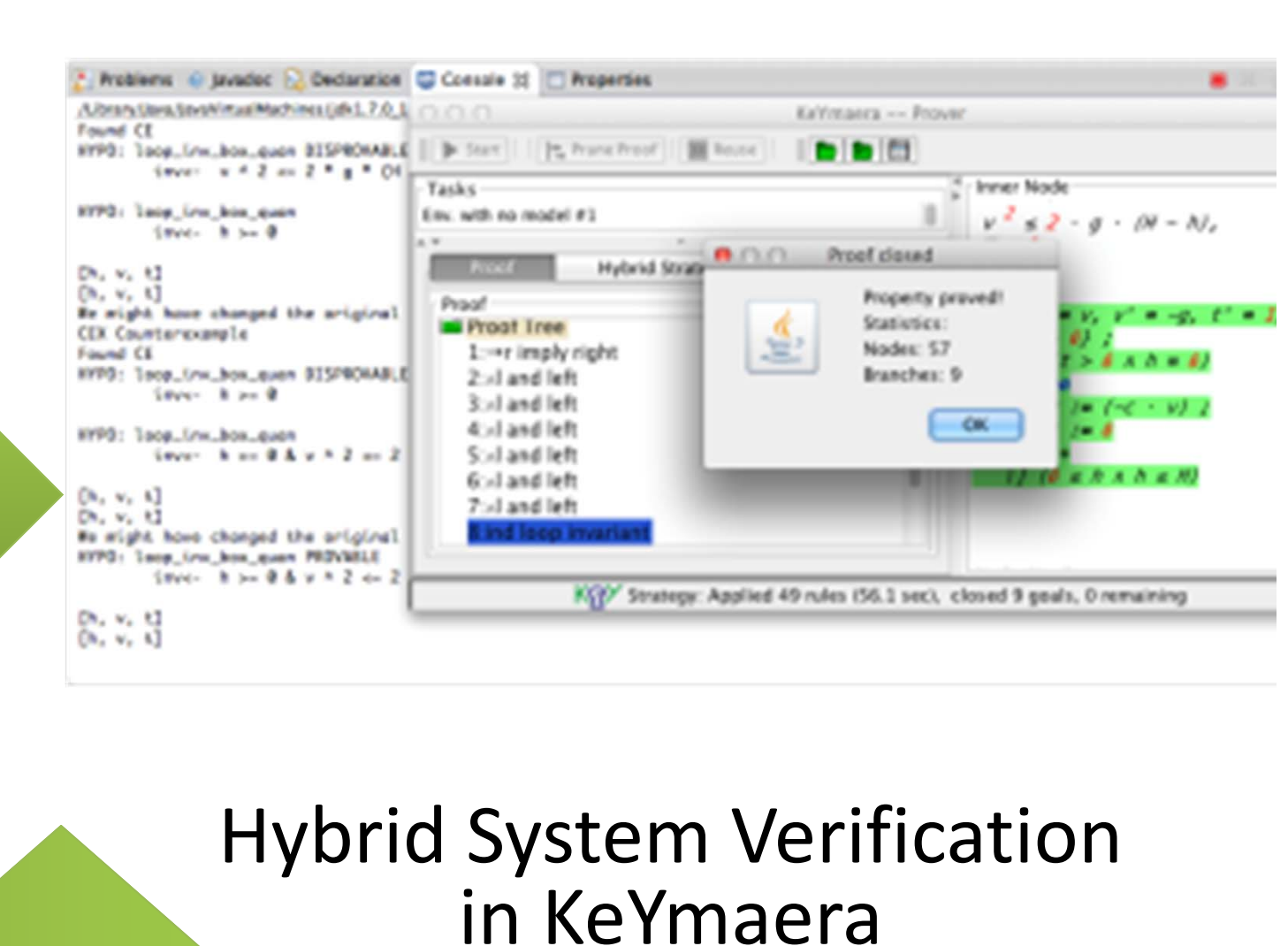
Syntax Highlighting and Code Completion

Syntax and Cross Reference Checking

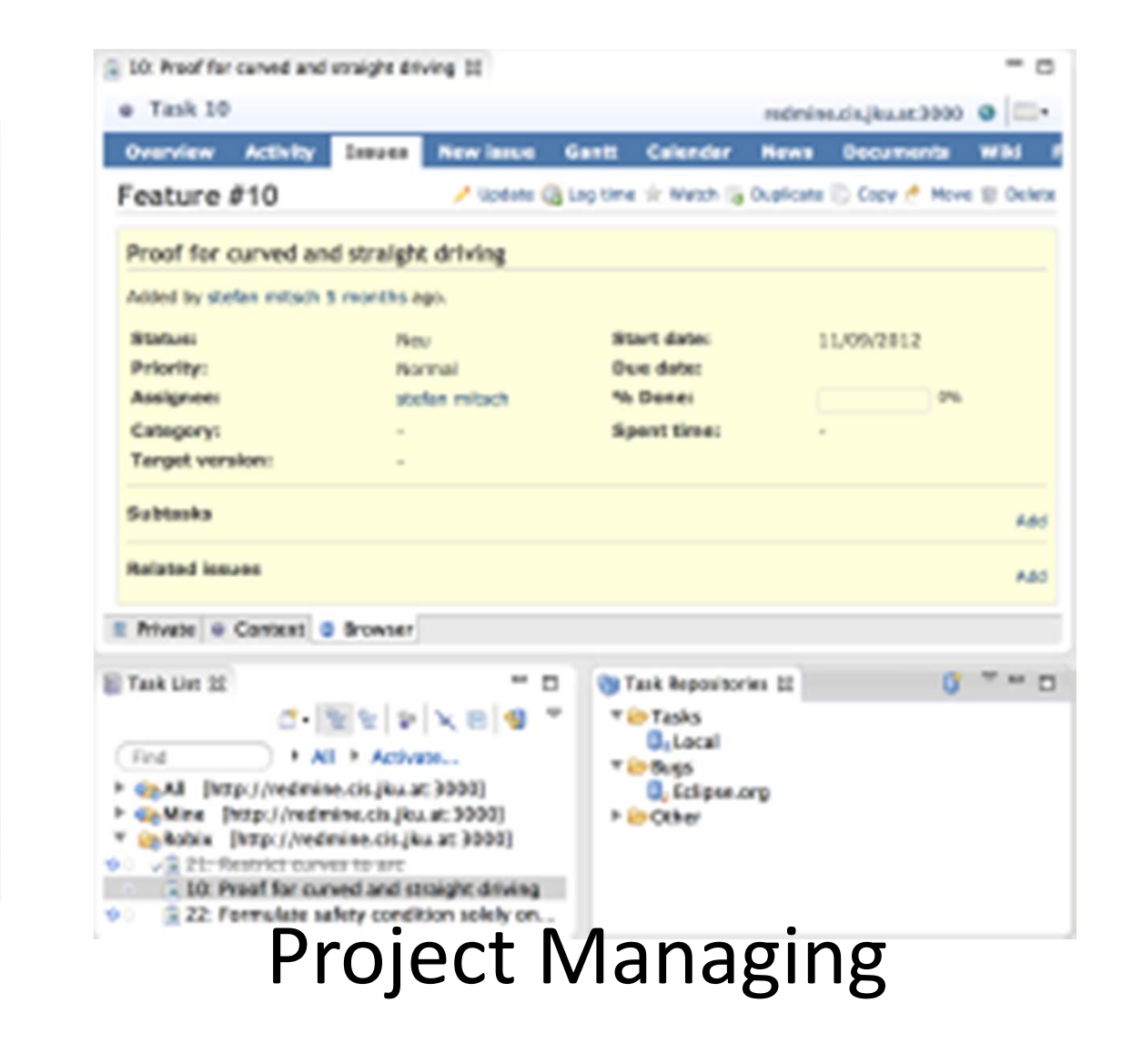
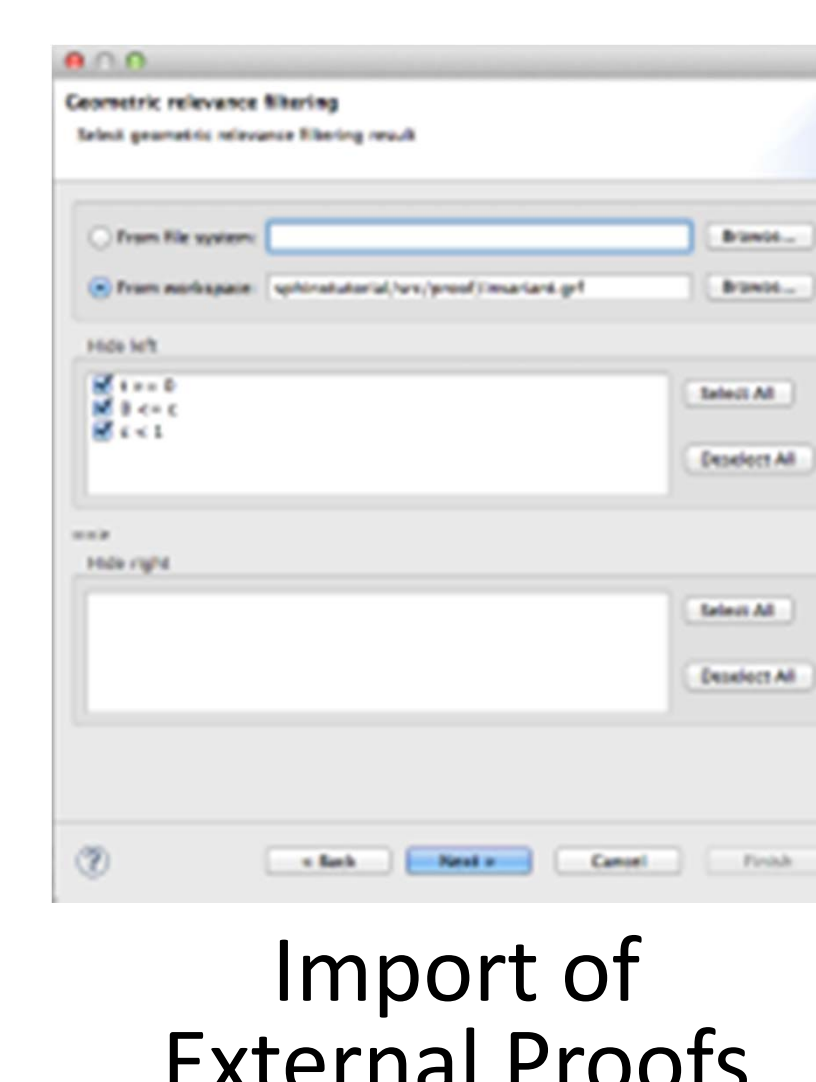
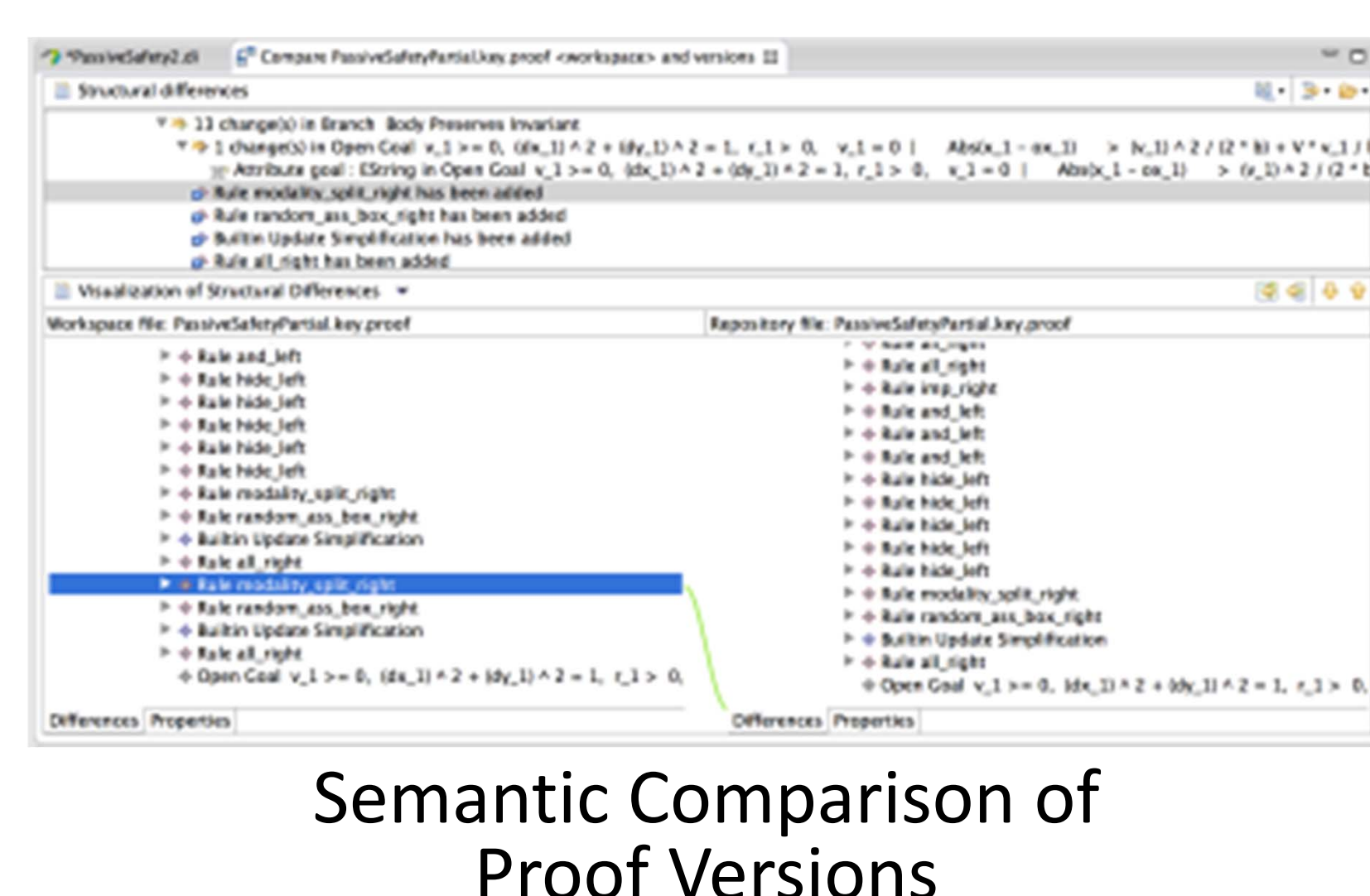
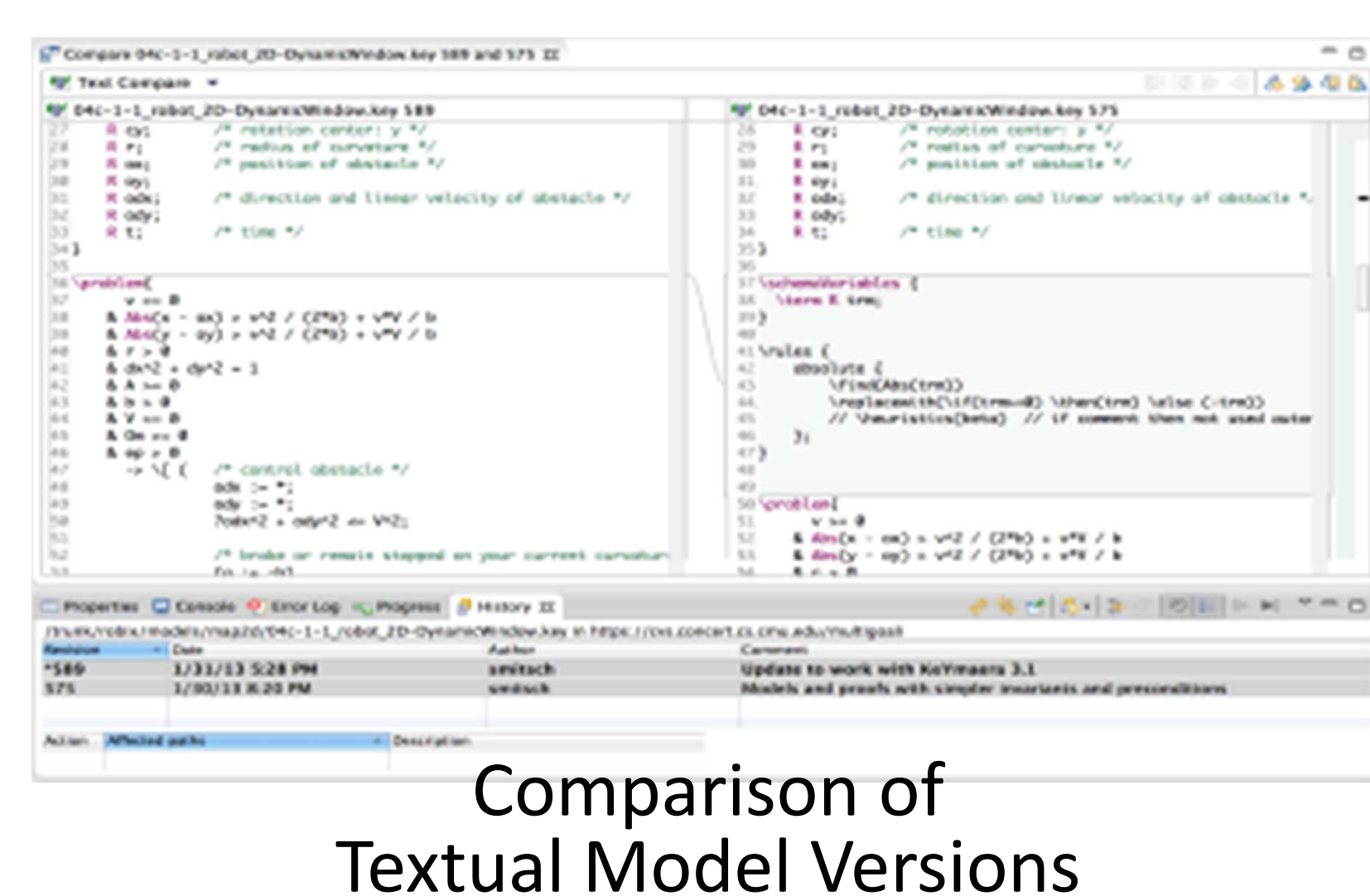
Transformation



Verification



Proof Collaboration



Project Info

Funding: FP7 Marie Curie
 Duration: NOV/2013 – OCT/2015
 Partners: Carnegie Mellon University